

Bipartite Matching

Introduction to Computational Mathematics

Instructor: **Tasuku Soma**

July 30, 2026

Outline

1. Min-max theorem for bipartite matching

- Integrality of LP (recap)
- Kőnig–Egerváry theorem

2. Unweighted bipartite matching

- Augmenting-path algorithm
- Revisiting the Kőnig–Egerváry theorem

3. Weighted bipartite matching

- Optimality condition
- Hungarian method

Outline

1. Min-max theorem for bipartite matching

- Integrality of LP (recap)
- Kőnig–Egerváry theorem

2. Unweighted bipartite matching

- Augmenting-path algorithm
- Revisiting the Kőnig–Egerváry theorem

3. Weighted bipartite matching

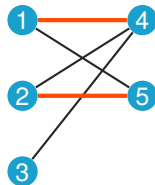
- Optimality condition
- Hungarian method

Bipartite matching

Weighted bipartite matching problem

Input $G = (V; E)$: a bipartite graph,
edge weights w_e ($e \in E$)

Output A maximum-weight matching M of G

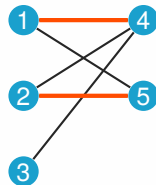


Bipartite matching

Weighted bipartite matching problem

Input $G = (V; E)$: a bipartite graph,
edge weights w_e ($e \in E$)

Output A maximum-weight matching M of G



IP formulation

$$\begin{aligned} &\text{maximize} && \sum_{e \in E} w_e x_e \\ &\text{subject to} && \sum_{e \in \delta(i)} x_e \leq 1 \quad (i \in V) \\ &&& x_e \in \{0, 1\} \quad (e \in E) \end{aligned}$$

$\delta(i)$: the set of edges incident to vertex i

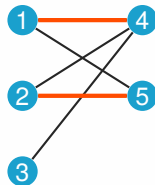
$$\begin{aligned} &\max && w^\top x \\ &\text{s.t.} && x_{14} + x_{15} &\leq 1 \\ &&& x_{24} + x_{25} &\leq 1 \\ &&& x_{34} &\leq 1 \\ &&& x_{14} + x_{24} + x_{34} &\leq 1 \\ &&& x_{15} + x_{25} &\leq 1 \\ &&& x_{14}, x_{15}, x_{24}, x_{25}, x_{34} \in \{0, 1\} \end{aligned}$$

Bipartite matching

Weighted bipartite matching problem

Input $G = (V; E)$: a bipartite graph,
edge weights w_e ($e \in E$)

Output A maximum-weight matching M of G



LP formulation

$$\begin{aligned} &\text{maximize} && \sum_{e \in E} w_e x_e \\ &\text{subject to} && \sum_{e \in \delta(i)} x_e \leq 1 \quad (i \in V) \\ &&& x_e \geq 0 \quad (e \in E) \end{aligned}$$

$$\begin{aligned} \max \quad & w^\top x \\ \text{s.t.} \quad & x_{14} + x_{15} \leq 1 \\ & x_{24} + x_{25} \leq 1 \\ & x_{34} \leq 1 \\ & x_{14} + x_{24} + x_{34} \leq 1 \\ & x_{15} + x_{25} \leq 1 \\ & x_{14}, x_{15}, x_{24}, x_{25}, x_{34} \geq 0 \end{aligned}$$

Recap: Total unimodularity of the coefficient matrix ensures an LP optimal solution with **0–1** entries!

Dual problem for bipartite matching

Primal (P)

$$\begin{array}{ll}\max & \sum_{e \in E} w_e x_e \\ \text{s.t.} & \sum_{e \in \delta(i)} x_e \leq 1 \quad (i \in V) \\ & x \geq 0\end{array}$$

Dual (D)

$$\begin{array}{ll}\min & \sum_{i \in V} y_i \\ \text{s.t.} & y_i + y_j \geq w_e \quad (e = ij \in E) \\ & y \geq 0\end{array}$$

The coefficient matrix of the dual problem (D) is also totally unimodular. Hence, if edge weights w_e ($e \in E$) are integers, then (D) has an integral optimal solution.

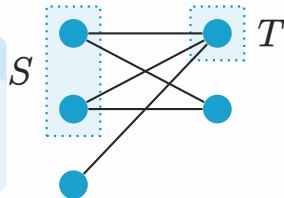
Kőnig–Egerváry theorem

$G = (V^+, V^-; E)$: bipartite graph with vertex sets V^+ and V^- .

Definition

$S \subseteq V^+, T \subseteq V^-$ is a **vertex cover**

$\stackrel{\text{def}}{\iff}$ for any edge $e = ij \in E$, either $i \in S$ or $j \in T$.



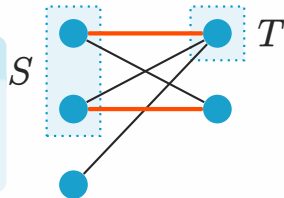
Kőnig–Egerváry theorem

$G = (V^+, V^-; E)$: bipartite graph with vertex sets V^+ and V^- .

Definition

$S \subseteq V^+, T \subseteq V^-$ is a **vertex cover**

$\stackrel{\text{def}}{\iff}$ for any edge $e = ij \in E$, either $i \in S$ or $j \in T$.



Lemma (Weak Duality)

For any matching M and vertex cover (S, T) , we have $|M| \leq |S| + |T|$.

(pf) Since M consists of disjoint edges, at least $|M|$ vertices are needed to cover M .



Kőnig–Egerváry theorem

Consider the previous LP with $w \equiv 1$. By integrality and strong duality, we obtain the following theorem.

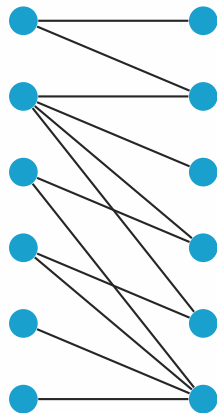
Theorem (Kőnig–Egerváry)

For any bipartite graph G , the following min-max relation holds:

$$\max_{M: \text{ matching}} |M| = \min_{(S,T): \text{ vertex cover}} |S| + |T|$$

Example

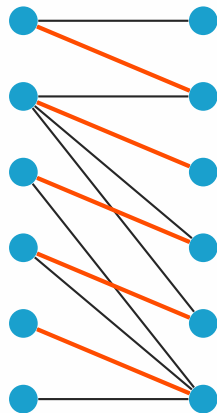
In the bipartite graph on the right,



Example

In the bipartite graph on the right,

- the maximum matching size is $|M| = 5$,



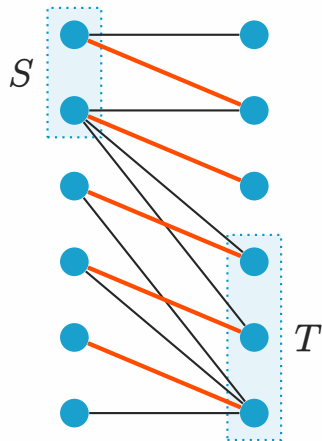
Example

In the bipartite graph on the right,

- the maximum matching size is $|M| = 5$,
- the minimum vertex-cover size is $|S| + |T| = 5$.

In general, to prove that a matching M is maximum in a bipartite graph, it suffices to present a vertex cover (S, T) satisfying

$$|M| = |S| + |T|.$$



Example

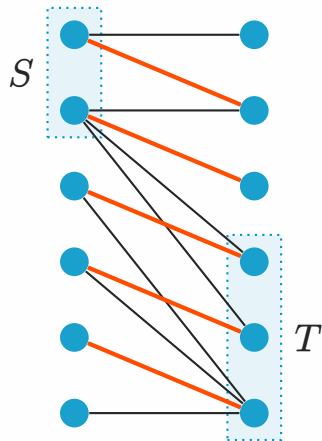
In the bipartite graph on the right,

- the maximum matching size is $|M| = 5$,
- the minimum vertex-cover size is $|S| + |T| = 5$.

In general, to prove that a matching M is maximum in a bipartite graph, it suffices to present a vertex cover (S, T) satisfying

$$|M| = |S| + |T|.$$

Such a vertex cover is a certificate of optimality of M (**good characterization**)



Outline

1. Min-max theorem for bipartite matching

- Integrality of LP (recap)
- König–Egerváry theorem

2. Unweighted bipartite matching

- Augmenting-path algorithm
- Revisiting the König–Egerváry theorem

3. Weighted bipartite matching

- Optimality condition
- Hungarian method

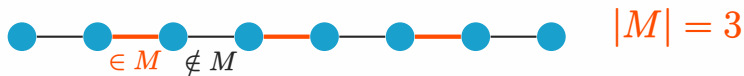
Augmenting paths

M : matching of G

Definition

A path P is an **augmenting path** (with respect to M) $\stackrel{\text{def}}{\iff}$

- 1 edges in $E \setminus M$ and in M appear alternately in P .
- 2 the two endpoints of P are unmatched in M .



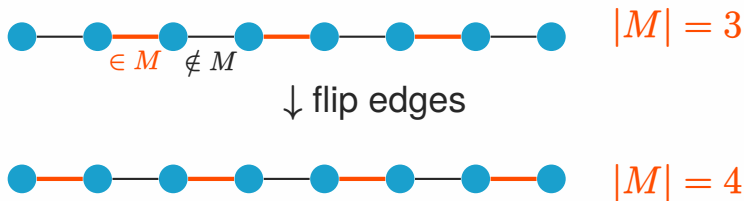
Augmenting paths

M : matching of G

Definition

A path P is an **augmenting path** (with respect to M) $\stackrel{\text{def}}{\iff}$

- 1 edges in $E \setminus M$ and in M appear alternately in P .
- 2 the two endpoints of P are unmatched in M .



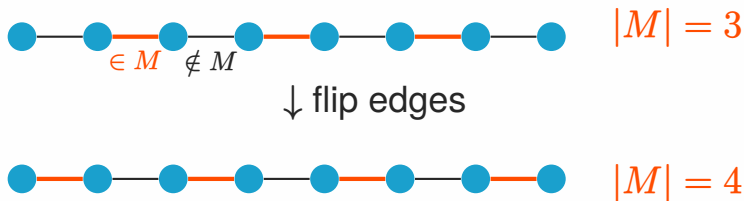
Augmenting paths

M : matching of G

Definition

A path P is an **augmenting path** (with respect to M) $\stackrel{\text{def}}{\iff}$

- 1 edges in $E \setminus M$ and in M appear alternately in P .
- 2 the two endpoints of P are unmatched in M .



Therefore, if M is maximum, then no augmenting path exists.

Augmenting paths

Lemma

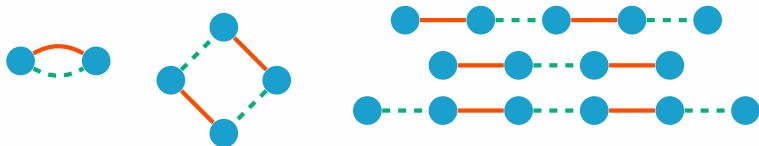
If M is not maximum, then an augmenting path exists.

Augmenting paths

Lemma

If M is not maximum, then an augmenting path exists.

(pf) Take two matchings M , M' with $|M| < |M'|$. Then, each connected component of $M + M'$ is either an alternating path or an even cycle.



Since $|M| < |M'|$, some connected component of $M + M'$ has more M' edges than M edges. This is an augmenting path for M . □

Augmenting-path algorithm

The lemma implies the following algorithm.

Augmenting-path algorithm

- 1: Let $M \leftarrow \emptyset$.
- 2: **while** there exists an augmenting path with respect to M :
- 3: Find an augmenting path P .
- 4: Flip edges along P to obtain a larger matching M .
- 5: **return** M

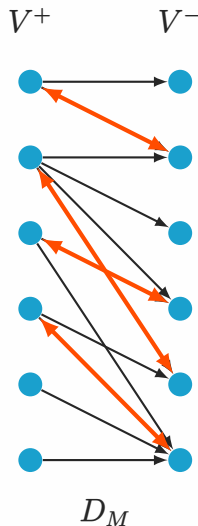
If an augmenting path can be found in A time, then the whole algorithm runs in $O(nA)$ time. $(n = |V|)$

Finding augmenting paths via a directed graph

For a matching M , orient edges of G as follows:

- edges in M : both directions,
- edges in $E \setminus M$: from V^+ to V^- .

Let the resulting digraph be D_M .



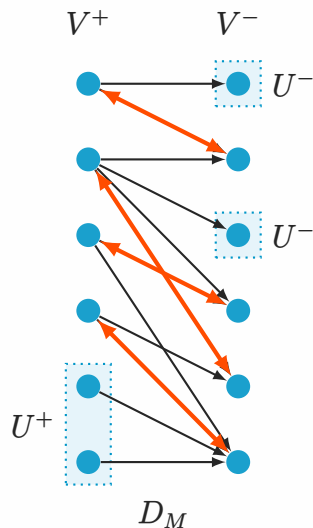
Finding augmenting paths via a directed graph

For a matching M , orient edges of G as follows:

- edges in M : both directions,
- edges in $E \setminus M$: from V^+ to V^- .

Let the resulting digraph be D_M . Also define

- $U^+ :=$ unmatched vertices in V^+ under M
- $U^- :=$ unmatched vertices in V^- under M



Finding augmenting paths via a directed graph

For a matching M , orient edges of G as follows:

- edges in M : both directions,
- edges in $E \setminus M$: from V^+ to V^- .

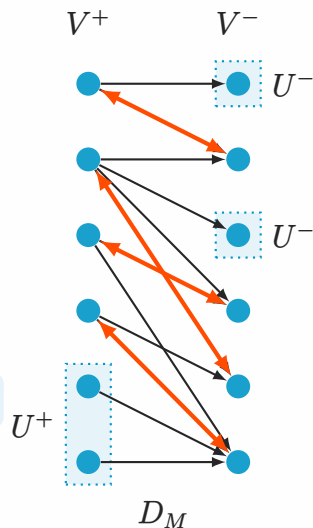
Let the resulting digraph be D_M . Also define

- $U^+ :=$ unmatched vertices in V^+ under M
- $U^- :=$ unmatched vertices in V^- under M

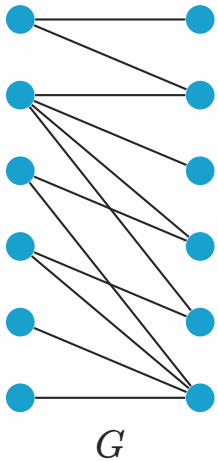
augmenting path $\longleftrightarrow$ directed path from U^+ to U^- in D_M

Hence, BFS finds an augmenting path in $O(m)$ time.

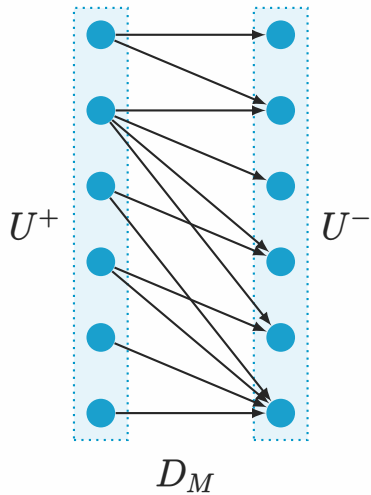
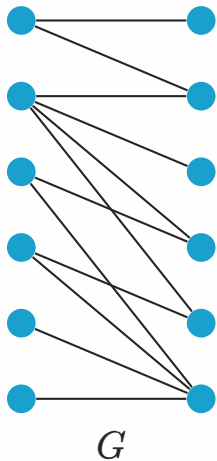
($m = |E|$)



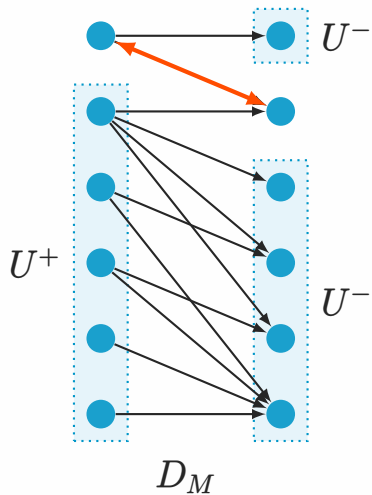
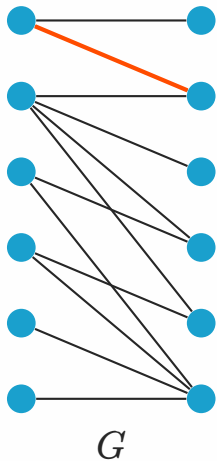
Example



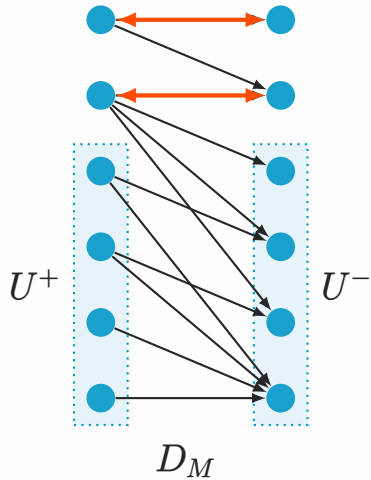
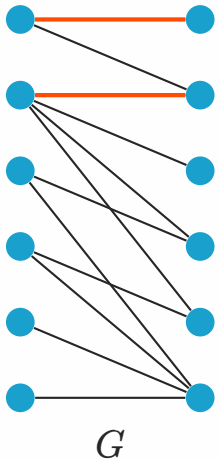
Example



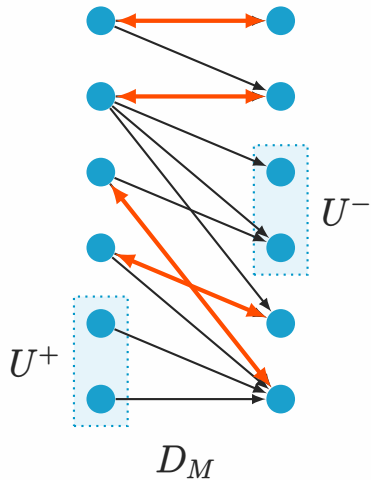
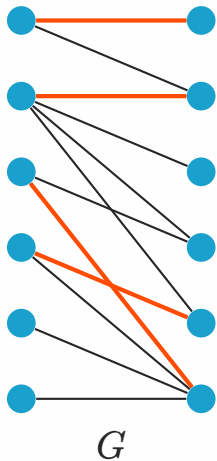
Example



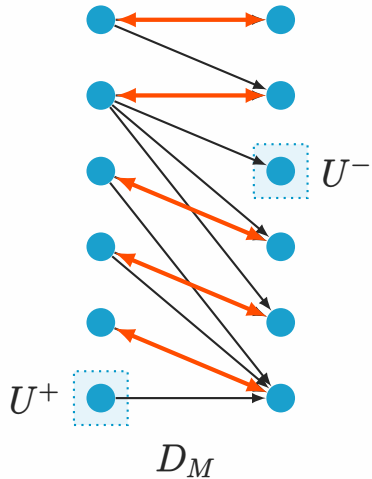
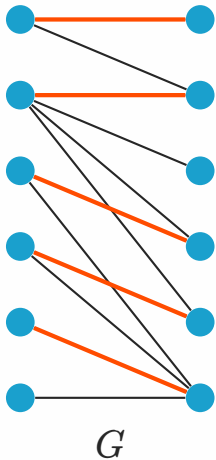
Example



Example



Example



[Finish]

Revisiting König–Egerváry

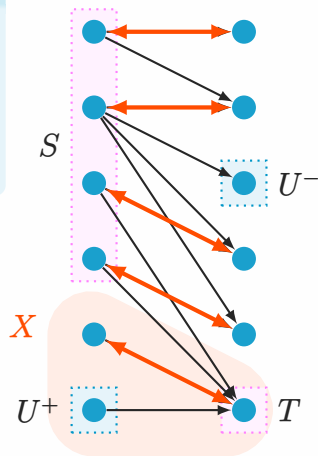
$$\max_{M: \text{matching}} |M| = \min_{(S, T): \text{vertex cover}} |S| + |T|$$

Theorem

At the termination of the algorithm, let X be the set of all vertices reachable from U^+ in D_M . Define

$$S := V^+ \setminus X, \quad T := V^- \cap X.$$

Then (S, T) is a minimum vertex cover.



Revisiting König–Egerváry

$$\max_{M: \text{matching}} |M| = \min_{(S, T): \text{vertex cover}} |S| + |T|$$

Theorem

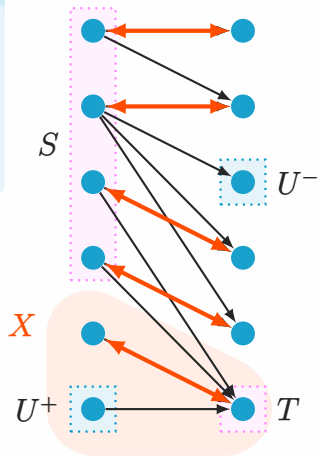
At the termination of the algorithm, let X be the set of all vertices reachable from U^+ in D_M . Define

$$S := V^+ \setminus X, \quad T := V^- \cap X.$$

Then (S, T) is a minimum vertex cover.

(pf) Why vertex cover? One can traverse any edge from left to right in D_M , so (S, T) is a vertex cover by definition.

Why minimum? Matching edges are bidirected, so their endpoints are either both in X or both not in X . Since no augmenting path exists, $X \cap U^- = \emptyset$. Hence every vertex in (S, T) covers exactly one edge of M . Thus, $|S| + |T| = |M|$. $\square$



Revisiting König–Egerváry

$$\max_{M: \text{matching}} |M| = \min_{(S, T): \text{vertex cover}} |S| + |T|$$

Theorem

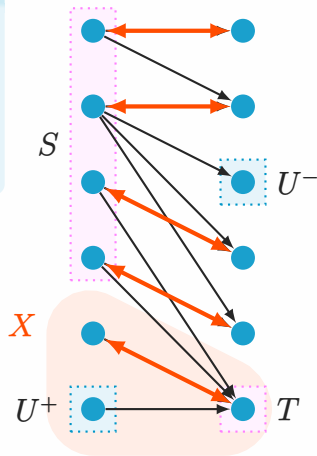
At the termination of the algorithm, let X be the set of all vertices reachable from U^+ in D_M . Define

$$S := V^+ \setminus X, \quad T := V^- \cap X.$$

Then (S, T) is a minimum vertex cover.

(pf) Why vertex cover? One can traverse any edge from left to right in D_M , so (S, T) is a vertex cover by definition.

Why minimum? Matching edges are bidirected, so their endpoints are either both in X or both not in X . Since no augmenting path exists, $X \cap U^- = \emptyset$. Hence every vertex in (S, T) covers exactly one edge of M . Thus,
 $|S| + |T| = |M|$. □



An algorithmic proof of the König–Egerváry theorem without LP!

Unweighted bipartite matching (summary)

Theorem

In a bipartite graph:

- *The augmenting-path algorithm finds a maximum matching M in $O(mn)$ time.*
 $(m = |E|, n = |V|)$
- *It also finds a vertex cover (S, T) satisfying $|M| = |S| + |T|$.*

Outline

1. Min-max theorem for bipartite matching

- Integrality of LP (recap)
- Kőnig–Egerváry theorem

2. Unweighted bipartite matching

- Augmenting-path algorithm
- Revisiting the Kőnig–Egerváry theorem

3. Weighted bipartite matching

- Optimality condition
- Hungarian method

Weighted bipartite (perfect) matching

A matching M is **perfect** $\stackrel{\text{def}}{\iff}$ every vertex is incident to $M \iff 2|M| = |V|$.

Weighted perfect bipartite matching problem

Input $G = (V; E)$: bipartite graph ($|V^+| = |V^-| = n/2$), edge weights w_e ($e \in E$)

Output A perfect matching M maximizing $w(M) := \sum_{e \in M} w_e$

Assume that G has at least one perfect matching in what follows.

Weighted bipartite (perfect) matching

A matching M is **perfect** $\stackrel{\text{def}}{\iff}$ every vertex is incident to $M \iff 2|M| = |V|$.

Weighted perfect bipartite matching problem

Input $G = (V; E)$: bipartite graph ($|V^+| = |V^-| = n/2$), edge weights w_e ($e \in E$)

Output A perfect matching M maximizing $w(M) := \sum_{e \in M} w_e$

Assume that G has at least one perfect matching in what follows.

Primal (P)

$$\begin{aligned} \max \quad & \sum_{e \in E} w_e x_e \\ \text{s.t.} \quad & \sum_{e \in \delta(i)} x_e = 1 \quad (i \in V) \\ & x \geq 0 \end{aligned}$$

Dual (D)

$$\begin{aligned} \min \quad & \sum_{i \in V} y_i =: y(V) \\ \text{s.t.} \quad & y_i + y_j \geq w_e \quad (e = ij \in E) \end{aligned}$$

Optimality Condition

Lemma (Optimality condition)

$M \subseteq E$, $y \in \mathbb{R}^V$ are optimal solutions
 $\iff$

- 1 M is a perfect matching,
- 2 y is feasible for (D),
- 3 $y_i + y_j = w_e \quad (e = ij \in M)$

Primal (P)

$$\begin{aligned} \max \quad & \sum_{e \in E} w_e x_e \\ \text{s.t.} \quad & \sum_{e \in \delta(i)} x_e = 1 \quad (i \in V) \\ & x \geq 0 \end{aligned}$$

Dual (D)

$$\begin{aligned} \min \quad & \sum_{i \in V} y_i =: y(V) \\ \text{s.t.} \quad & y_i + y_j \geq w_e \quad (e \in E) \end{aligned}$$

Optimality Condition

Lemma (Optimality condition)

$M \subseteq E$, $y \in \mathbb{R}^V$ are optimal solutions
 $\iff$

- ❶ M is a perfect matching,
- ❷ y is feasible for (D),
- ❸ $y_i + y_j = w_e \quad (e = ij \in M)$

- a feasible solution of (D) is called a **w-cover**,
- edges satisfying condition (3) are said to be **tight** (w.r.t. y).

Primal (P)

$$\begin{aligned} \max \quad & \sum_{e \in E} w_e x_e \\ \text{s.t.} \quad & \sum_{e \in \delta(i)} x_e = 1 \quad (i \in V) \\ & x \geq 0 \end{aligned}$$

Dual (D)

$$\begin{aligned} \min \quad & \sum_{i \in V} y_i =: y(V) \\ \text{s.t.} \quad & y_i + y_j \geq w_e \quad (e \in E) \end{aligned}$$

Hungarian method

The algorithm maintains a matching M and a w -cover y satisfying (2)(3), and updates them until (1) is satisfied.

Definition

For a w -cover y , define a subgraph $G_y = (V^+, V^-, E_y)$ of G by

$$E_y = \{e = ij \in E : y_i + y_j = w_e\}$$

That is, G_y keeps only tight edges with respect to y .

Lemma

If G_y has a **perfect** matching, then it is a maximum-weight matching.

(pf) Optimality condition!



Hungarian method

What if G_y has no perfect matching?

→ We can update y and improve the objective value of (D).

Hungarian method

What if G_y has no perfect matching?

→ We can update y and improve the objective value of (D).

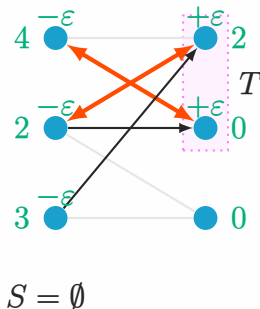
Lemma

Suppose G_y has no perfect matching. Let (S, T) be a minimum vertex cover of G_y . Define

$\varepsilon := \min\{y_i + y_j - w_e : e = ij \in E, i \notin S, j \notin T\}$. Let y' be

$$y'_i = \begin{cases} y_i - \varepsilon & (i \in V^+ \setminus S) \\ y_i + \varepsilon & (i \in V^- \cap T) \\ y_i & (\text{otherwise}) \end{cases}$$

Then y' is a w -cover with $y'(V) < y(V)$.



Proof

Why y' is a w -cover?

$$\varepsilon := \min\{y_i + y_j - w_e : e = ij \in E, i \notin S, j \notin T\}.$$
$$y'_i = \begin{cases} y_i - \varepsilon & (i \in V^+ \setminus S) \\ y_i + \varepsilon & (i \in V^- \cap T) \\ y_i & (\text{otherwise}) \end{cases}$$

- The only constraints $y_i + y_j \geq w_e$ ($e = ij \in E$) that could become violated after the update are those with $i \notin S, j \notin T$.
- By the definition of ε , feasibility is preserved.

Proof

$$\varepsilon := \min\{y_i + y_j - w_e : e = ij \in E, i \notin S, j \notin T\}.$$
$$y'_i = \begin{cases} y_i - \varepsilon & (i \in V^+ \setminus S) \\ y_i + \varepsilon & (i \in V^- \cap T) \\ y_i & (\text{otherwise}) \end{cases}$$

Why y' is a w -cover?

- The only constraints $y_i + y_j \geq w_e$ ($e = ij \in E$) that could become violated after the update are those with $i \notin S, j \notin T$.
- By the definition of ε , feasibility is preserved.

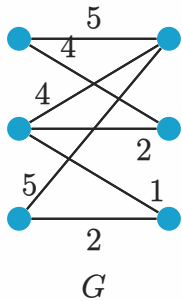
Why $y'(V) < y(V)$?

- $y'(V) = y(V) - \varepsilon(|V^+ \setminus S| - |T|) = y(V) - \varepsilon(n/2 - |S| - |T|)$.
- Since G_y has no perfect matching, we have $|S| + |T| < n/2$ by König–Egerváry theorem.
- Thus it suffices to show $\varepsilon > 0$. Because (S, T) is a vertex cover of G_y , any edge $e = ij \in E$ with $i \notin S, j \notin T$ is not tight, i.e., $y_i + y_j - w_e > 0$. □

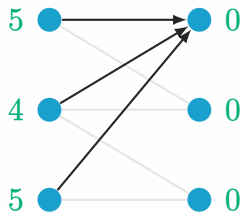
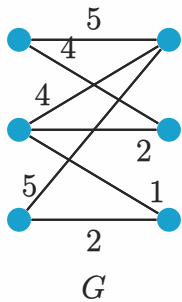
Hungarian method

```
1: Set  $y_i := \max_{e \in \delta(i)} w_e$  ( $i \in V^+$ ),  $y_j := 0$  ( $j \in V^-$ ). //  $y$  is a trivial  $w$ -cover
2: while True :
3:     Find a maximum (unweighted) matching  $M$  of  $G_y$ . //  $O(mn)$  time
4:     if  $M$  is perfect :
5:         return  $M$  // By optimality condition,  $M$  is maximum-weight
6:     else //  $w$ -cover update
7:         Let  $X$  be the set of vertices reachable from  $U^+$  in  $D_M(y)$ .
            //  $(S, T) = (V^+ \setminus X, V^- \cap X)$  is a minimum vertex cover of  $G_y$ 
8:          $\varepsilon := \min\{y_i + y_j - w_{ij} : i \in V^+ \cap X, j \in V^- \setminus X\}$ 
9:          $y_i \leftarrow y_i - \varepsilon$  ( $i \in V^+ \cap X$ ),  $y_j \leftarrow y_j + \varepsilon$  ( $j \in V^- \cap X$ )
```

Example

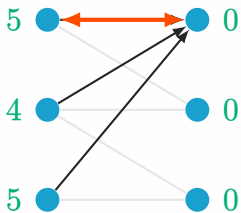
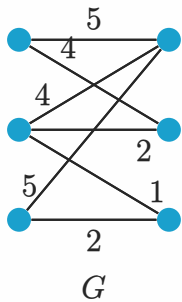


Example



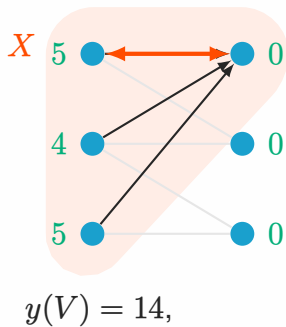
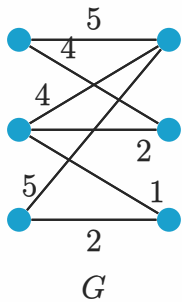
$$y(V) = 14,$$

Example

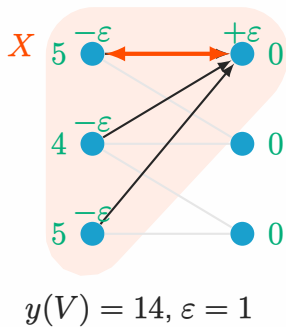
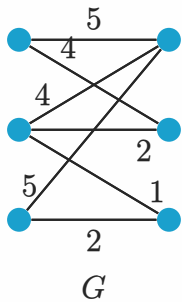


$$y(V) = 14,$$

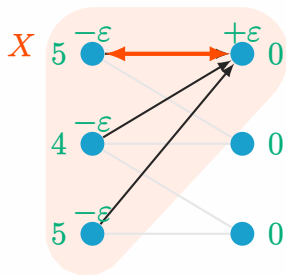
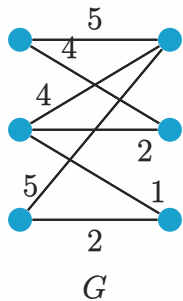
Example



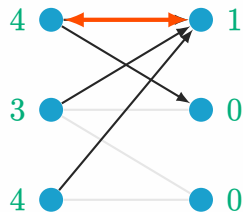
Example



Example

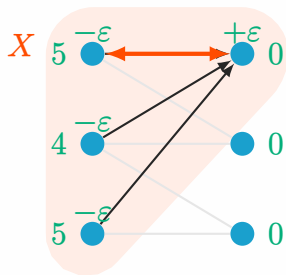
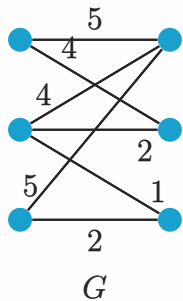


$$y(V) = 14, \varepsilon = 1$$

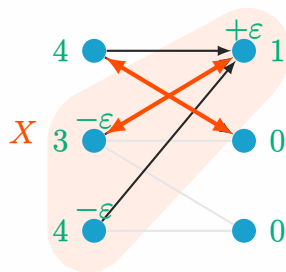


$$y(V) = 12,$$

Example

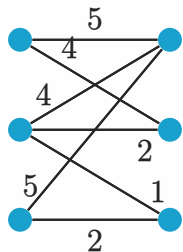


$$y(V) = 14, \epsilon = 1$$

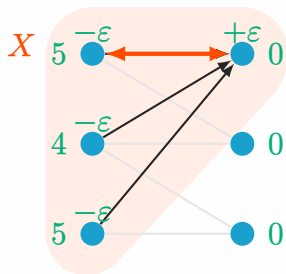


$$y(V) = 12, \epsilon = 1$$

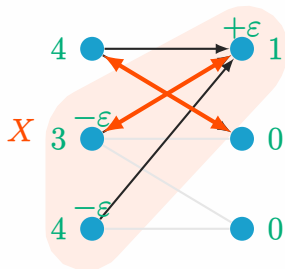
Example



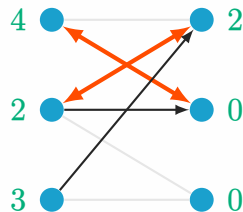
G



$$y(V) = 14, \varepsilon = 1$$

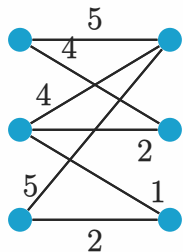


$$y(V) = 12, \varepsilon = 1$$

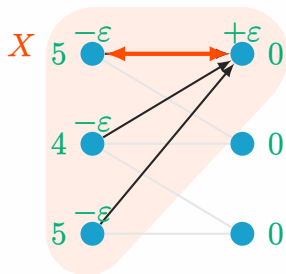


$$y(V) = 11,$$

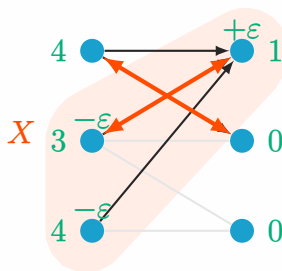
Example



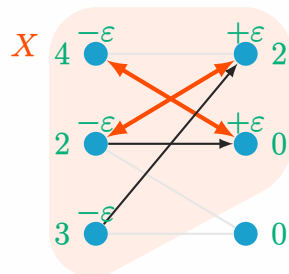
G



$$y(V) = 14, \varepsilon = 1$$

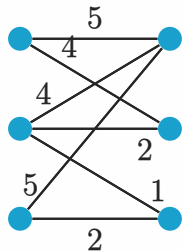


$$y(V) = 12, \varepsilon = 1$$

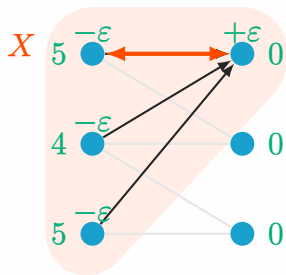


$$y(V) = 11, \varepsilon = 1$$

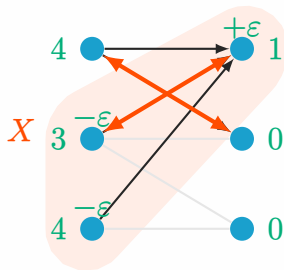
Example



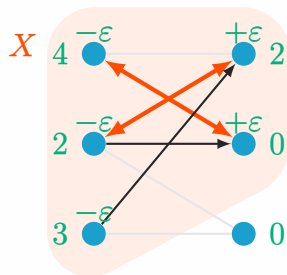
G



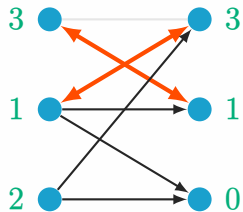
$$y(V) = 14, \epsilon = 1$$



$$y(V) = 12, \epsilon = 1$$

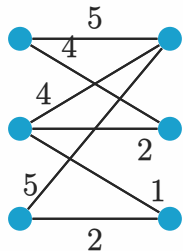


$$y(V) = 11, \epsilon = 1$$

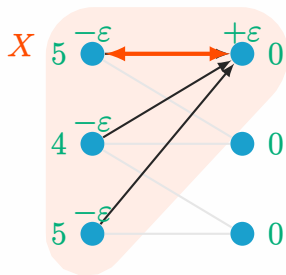


$$y(V) = 10$$

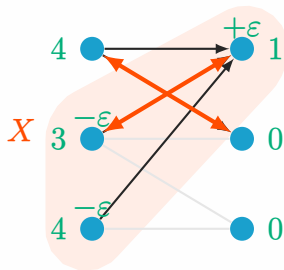
Example



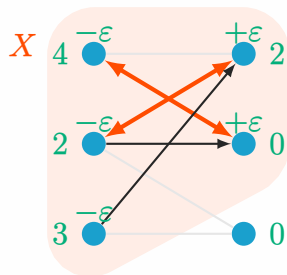
G



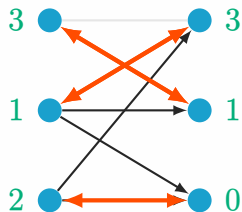
$$y(V) = 14, \epsilon = 1$$



$$y(V) = 12, \epsilon = 1$$



$$y(V) = 11, \epsilon = 1$$



$$y(V) = 10 = w(M) \text{ [END]}$$

Analysis of the Hungarian method

Theorem

The Hungarian method finds a maximum-weight perfect matching and a minimum w -cover in $O(mn^3)$ time.

($m = |E|$, $n = |V|$)

Analysis of the Hungarian method

Theorem

The Hungarian method finds a maximum-weight perfect matching and a minimum w -cover in $O(mn^3)$ time. $(m = |E|, n = |V|)$

- During the algorithm, $|M|$ never decreases.

→ M is updated at most $n/2$ times.

Analysis of the Hungarian method

Theorem

The Hungarian method finds a maximum-weight perfect matching and a minimum w -cover in $O(mn^3)$ time. $(m = |E|, n = |V|)$

- During the algorithm, $|M|$ never decreases.
 - ($\because$) when y is updated to y' , the maximum matching M in G_y is still a matching in $G_{y'}$.
 - $\longrightarrow M$ is updated at most $n/2$ times.

Analysis of the Hungarian method

Theorem

The Hungarian method finds a maximum-weight perfect matching and a minimum w -cover in $O(mn^3)$ time. $(m = |E|, n = |V|)$

- During the algorithm, $|M|$ never decreases.
 - ($\because$) when y is updated to y' , the maximum matching M in G_y is still a matching in $G_{y'}$.
 - $\longrightarrow M$ is updated at most $n/2$ times.
- When y is updated without increasing $|M|$, the edges achieving the minimum in the definition of ε make the reachable set X strictly larger.
 - $\longrightarrow$ after at most n such updates of y , $|M|$ must increase.

Analysis of the Hungarian method

Theorem

The Hungarian method finds a maximum-weight perfect matching and a minimum w -cover in $O(mn^3)$ time. $(m = |E|, n = |V|)$

- During the algorithm, $|M|$ never decreases.
 - ($\because$) when y is updated to y' , the maximum matching M in G_y is still a matching in $G_{y'}$.
 - $\longrightarrow M$ is updated at most $n/2$ times.
- When y is updated without increasing $|M|$, the edges achieving the minimum in the definition of ε make the reachable set X strictly larger.
 - $\longrightarrow$ after at most n such updates of y , $|M|$ must increase.

Therefore, the total number of iterations is $O(n^2)$.



Summary

- Basic LP-based ideas in combinatorial optimization (integral polyhedra and totally unimodular matrices)
- Using LP integrality, we proved the min-max theorem for bipartite matching (Kőnig–Egerváry theorem)
- Combinatorial algorithms that do not use LP
 - augmenting-path algorithm for unweighted bipartite matching
 - Hungarian method for weighted bipartite perfect matching